

International Association of Wildland Fire

Pixels to pyrometrics: UAS-derived infrared imagery to evaluate and monitor prescribed fire behaviour and effects

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Received: 16 April 2024 Accepted: 21 October 2024 Published: 20 November 2024

Cite this: O'Neill L *et al.* (2024) Pixels to pyrometrics: UAS-derived infrared imagery to evaluate and monitor prescribed fire behaviour and effects. *International Journal of Wildland Fire* **33**, WF24067. doi:10.1071/WF24067

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ABSTRACT

Background. Prescribed fire is vital for fuel reduction and ecological restoration, but the effectiveness and fine-scale interactions are poorly understood. Aims. We developed methods for processing uncrewed aircraft systems (UAS) imagery into spatially explicit pyrometrics, including measurements of fuel consumption, rate of spread, and residence time to quantitatively measure three prescribed fires. Methods. We collected infrared (IR) imagery continuously (0.2 Hz) over prescribed burns and one experimental calibration burn, capturing fire progression and combustion for multiple hours. Key results. Pyrometrics were successfully extracted from UAS-IR imagery with sufficient spatiotemporal resolution to effectively measure and differentiate between fires. UAS-IR fuel consumption correlated with weight-based measurements of 10 1-m² experimental burn plots, validating our approach to estimating consumption with a costeffective UAS-IR sensor (R^2 = 0.99; RMSE = 0.38 kg m⁻²). Conclusions. Our findings demonstrate UAS-IR pyrometrics are an accurate approach to monitoring fire behaviour and effects, such as measurements of consumption. Prescribed fire is a fine-scale process; a ground sampling distance of <2.3 m² is recommended. Additional research is needed to validate other derived measurements. Implications. Refined fire monitoring coupled with refined objectives will be pivotal in informing fire management of best practices, justifying the use of prescribed fire and providing quantitative feedback in an uncertain environment.

Keywords: fire effects, fire radiative energy (FRE), fire radiative power (FRP), fire rate of spread, fuel consumption, image stabilisation, thermal imagery, unmanned aerial vehicles (UAV), uncrewed aircraft systems (UAS).

Introduction

Prescribed fires differ from wildfires in three aspects: (1) they are intentional and planned; (2) they burn with relatively lower intensities; and (3) are designed to achieve specific outcomes. During the planning phase, managers can manipulate the burn conditions (seasonality, firing pattern, weather) to achieve specific prescription objectives, such as reducing dead and down fuel loadings and understorey vegetation, retaining dominant trees and snags, and modifying forest structure and composition to the natural range of variability (Fernandes and Botelho 2003; Fulé *et al.* 2012; Reynolds *et al.* 2013; Ryan *et al.* 2013; Waring *et al.* 2016). The planning and outcome of prescribed fires has much more potential to be informed by research than full suppression wildfire operations, due to the fact that burns are conducted with the intention of achieving a desired prescription (Hiers *et al.* 2020). There is a growing need for research using spatially explicit tools to understand prescribed fire processes and quantitatively inform land management on treatment effectiveness and best practices (Hiers *et al.* 2020).

Fire behaviour is a complex interaction of many exogenous (weather, fuel loading and moisture, topography, etc.) and endogenous (fire line patterns, convective heating, fire-weather feedbacks) factors (Parsons *et al.* 2017; O'Brien *et al.* 2018; Hudak *et al.* 2020). The spatial pattern of fuel is a multiscale property, heterogeneous at fine ($<1 \text{ m}^2$) and

coarse (>1 m²) scales (Loudermilk et al. 2012; Rowell et al. 2020). Consequently, fire is also a multiscale process, interacting with environmental factors at many scales depending on the intensity of the fire (Cruz et al. 2022). At low intensities, submeter fuel variability is linked to submeter fire variability (Loudermilk et al. 2012; Moran 2019; Cruz et al. 2022). While this spatial scale is critical for understanding ecological fire effects and processes (O'Brien et al. 2018), fire monitoring is unable to capture the detail needed to characterise these complex fire and fuel patterns (Hiers et al. 2020). Fire behaviour is often assessed by observing fire, such as estimating rate of spread by timing the fire front's progression between points of known distances (Rothermel and Deeming 1980). Ocular estimation comes with ocular bias, restricting our understanding of fire behaviour with respect to fuels and effects.

Uncrewed aircraft systems (UAS) and new digital tools may serve to support prescribed fire management and research, as seen in other ecological applications (de Almeida et al. 2020; Jain et al. 2020; Boroujeni et al. 2024). Pyrometrics, which is the application of statistical, mathematical, and computational methods to characterise fire and fire effects, has undergone a transformation with the adoption of UAS and other sub-orbital remote sensing platforms (Nitoslawski et al. 2021). Pyrometric research using UAS and piloted aircrafts draws on theoretical and lab-tested work to produce spatially explicit measurements of fine-scale fire patterns and processes (O'Brien et al. 2015; Hudak et al. 2016; Moran et al. 2019, 2022; Bright et al. 2022; Schumacher et al. 2022). Pyrometrics derived specifically from UAS-borne imagery include energy release (Moran et al. 2022), rate of spread (Moran et al. 2019; Gowravaram et al. 2022; Schumacher et al. 2022), tree crown scorch (Moran et al. 2022), burn severity (Hillman et al. 2021), and fire behaviour interactions (Filkov et al. 2021). UAS-derived data bridges the spatiotemporal gap between satellite sensors and field data, potentially providing a cost-effective method of monitoring and studying fine-scale prescribed fire patterns.

Using infrared (IR) imagery to measure fire energy release, rate of spread, and other fire behaviour characteristics is common in fire ecology research (Wooster et al. 2005; Kremens et al. 2012; Smith et al. 2013; Mathews et al. 2016; Johnston et al. 2018; Sagel et al. 2021). However, most studies are limited to the laboratory setting or experimental burns where ample time is provided to set up equipment in a semi-controlled environment and cameras are mounted in fixed positions. To our knowledge, no research has tested the accuracy of UAS-borne IR imagery in estimating consumption of surface fuel, especially with a consumer-grade sensor. IR imagery can be used to estimate fuel consumption with multiple approaches appearing in literature (Wooster 2002; Wooster et al. 2005; Freeborn et al. 2008; Smith et al. 2013; Hudak et al. 2016; Klauberg et al. 2018). These approaches use a radiometrically calibrated IR image stack of the entire combustion process and

then integrate power over time to calculate energy release. Radiative energy is then converted to fuel consumed using either the energy density or the moisture of the fuel. With the onset of UAS, using infrared imagery to measure fire behaviour has become much more attractive to research and local agencies. Consumer-grade UAS are cost-effective, accessible, and can be easily deployed for fire monitoring use. Conversely, UAS-borne (and similar crewed platforms) IR sensors often have a low saturation threshold, so maximum fire temperatures may not be measured (Moran et al. 2019). The imagery is unstable and requires colocation and registration pre-processing (Valero et al. 2021). Additionally, UAS often are limited in flight time, so post-frontal combustion may be omitted (Moran et al. 2022). Despite all these challenges, UAS may be able to deliver the missing piece of information to connect post-fire effects with pre-fire fuel, informing our understanding of fire as a mechanistic process.

We initiated this study to evaluate the accuracy of UAS to quantitatively monitor and measure prescribed fire. We collected UAS-derived radiometric, IR imagery of a calibration experimental burn and three prescribed fires to: (1) validate the accuracy of UAS-based radiative energy surface fuel consumption estimates; and (2) use extracted pyrometrics (consumption, rate of spread, and residence time) to characterise prescribed fire behaviour and effects. We expected UAS-derived IR imagery would be an accurate approach to estimating surface fuel consumption and that extracted pyrometrics would characterise the variability between and within each prescribed fire.

Materials and methods

UAS platform and imagery collection

Prior to ignition, we launched the UAS to collect images of the fire behaviour. We positioned the UAS directly overhead the centre of the plots (described in section 'Prescribed fire imagery aquisition and analysis'), facing north and at 122 m above ground, and collected thermal imagery at 0.2 Hz (5 s interval) to capture ignitions and post-frontal fuel consumption. All UAS imagery was collected with an Autel Evo II 640t UAS, featuring a 48-megapixel colour camera and a 0.32-megapixel IR camera. The thermal camera is an Infiniray Micro III Lite 640 (Yantai, Shandong, China) uncooled radiometric sensor that samples at the longwave IR wavelengths, 8-14 µm with a temperature range of 0-650°C. At 122 m, the colour and infrared sensors ground sampling distance are 1.2 and 14 cm pixel⁻¹, respectively. With a realistic flight time of 30 min, five batteries, and field charging array, we could perpetually hover the UAS over the fire. About every 30 min, we paused thermal image sampling to swap the UAS battery, returning to the same altitude and location to resume monitoring. It is important to note we used the low gain setting to capture infrared images, which is less sensitive than the high gain but can

sense at the full operational range of the camera. Saturation refers to the highest temperature at which a sensor can accurately measure. Above this point, the sensor cannot differentiate between temperatures and may provide inaccurate readings. Sensor saturation can lead to underestimation of the energy produced, which is critical to precisely estimating energy release of combusting biomass via IR sensing. The IR sensor used in this project is certified by the manufacturer to 650°C, below the maximum potential combustion temperature (Paugam et al. 2013; Moran et al. 2019) and is subject to the dependency of flame emissivity on flame depth (Johnston et al. 2014), but we selected this camera because of its affordability and simple use. While the camera limitation should be acknowledged, most prescribed fire typically involves low intensity fire, which is well below the maximum combustion temperature and IR saturation temperature (Iverson et al. 2004; Kennard et al. 2005).

Thermal imagery preprocessing

The thermal imagery acquired from the UAS in raw form was a 16-bit 1-band raster, with no geolocation information, requiring appropriate processing for quantitative spatial analysis. The three steps used to process the imagery are: (1) conversion to temperature (see Supplementary material Eqn S1); (2) stabilisation; and (3) georectification. All pyrometrics were derived from IR imagery preprocessed using the methods described, similar to Moran *et al.* (2019, 2022) and using equations developed and applied by O'Brien *et al.* (2015) and Hudak *et al.* (2016). After testing four stabilisation algorithms and the use of a mask to remove burning pixels, we determined an Enhanced Correlation Coefficient algorithm without a fire-mask was the best stabilising model for this study, used for all imagery hereafter (Fig. S2). The end result of the pre-processing were georeferenced,

temperature-calibrated image stacks, where each pixel represents fire radiative power (FRP, W m⁻²) at a specified location. Each image stack can be thought of as a time-lapse of fire behaviour. FRP is then converted to fire radiative energy (FRE, MJ m²) by taking the integral of FRP over time. For more details on thermal imagery preprocessing, see Supplementary material S1.

Experimental calibration burn

We conducted an experimental burn to validate the estimates of surface fuel consumption derived from a UASmounted IR sensor. To do this, we burned known quantities of ponderosa fuel, measured the consumption directly by weighing fuel before and after the burn (hereafter weightbased), and compared it to consumption estimates derived from the UAS-IR imagery (hereafter UAS-based). Images were processed as described above to generate FRE of each plot. We then calculated fuel consumption using two published estimators (Eqns 1 and 2) and compared it with consumption calculated by weighing fuel before and after. This calibration burn compared the UAS-IR method of estimating consumption with a validated, ground-truth counterpart in a variety of fuel conditions.

We precisely weighed and homogeneously arranged variable amounts of dry ponderosa litter and cut logs (<15 cm in diameter) in 10 1-m² plots. We selected coarse woody debris (CWD) and litter quantities that are representative of fuel conditions encountered in ponderosa forests, (Table 1). Roccaforte *et al.* (2012) reported a maximum 10 and 0.8 kg m⁻² of CWD and litter loadings, given the bulk density of litter is ~4 Mg ha⁻¹ cm⁻¹ (Stephens *et al.* 2004). We doubled each of these quantities to account for the spatial heterogeneity typical of surface fuels. The design of the 10 plots was to burn across a range of fuel loads at

Table 1.	Calibration burn fuel loading, actual consumption measured in the field (weight-based), and estimated UAS consumption (UAS-based
using Eqn	2) of each 1-m ² plot designed to represent the range of fuel loading conditions encountered in south-western ponderosa forests.

Plot	Dry wood weight (kg)	Dry litter weight (kg)	Wood:litter ratio	Fuel moisture (%)	Weight-based consumption (kg)	UAS-based consumption (kg)	Percent consumption (weight- based) (%)	Percent consumption (UAS-based) (%)
1	1.83	0.43	4.3	11	2.14	2.44	95	108
2	3.48	0.89	3.9	11	4.30	4.29	98	98
3	5.36	1.78	3.0	11	7.00	7.19	98	101
4	7.18	0.45	16	11	7.49	8.22	98	107
5	8.93	0.90	9.9	11	9.64	10.64	98	108
6	10.74	1.78	6.0	11	12.26	12.15	98	97
7	12.53	0.45	28	11	12.70	13.51	98	104
8	14.26	0.89	16	11	14.67	15.95	97	105
9	16.06	1.78	9.0	11	17.50	18.19	98	102
10	17.79	1.78	10	11	19.07	21.54	97	110

different ratios of litter and wood. We first stratified our plots by wood weight (including moisture-related weight), arranging wood from 2 to 20 kg at 2-kg intervals at each plot. To ensure we sampled variable litter and wood ratios that were representative of the sites, we then added ponderosa needle cast collected nearby the calibration plot at weights of 0.5 kg, 1 kg, and 2 kg (Table 1). Fuel moisture was sampled immediately prior to ignitions from three wood and three litter samples and calculated as the relative loss of water content after drying in an oven at 70°C for 24-h intervals until the dry weight was stable (Keane 2015).

Plots were ignited with a flare to avoid adding fuel and energy to the plot during ignition. We collected IR imagery at 0.2 Hz, 61 m above ground for 2 h and 15 min. Consumption was immediately stopped by spraying all the plots with water and extinguishing any smouldering. After the burn, all remaining ash and charred wood was collected, dried until the weight stabilised, and weighed to calculate the total consumption following eqn 3 in Smith et al. (2005). This approach does not account for incombustible material in the fuel, the proportional combustion completeness, and potential loss of ash from convective heat and wind. A solution is to use equation 12 from Smith et al. (2005) that accounts for the entire combustion budget by calculating the loss on ignition of pre- and post-fire fuel components. Nonetheless, the simple subtraction method used here calculates fuel consumption to $\sim 10\%$ accuracy of the more time-consuming approach (Smith et al. 2005).

We compared methods for fuel consumption (FC) estimation using two different FRE-based approaches (Smith *et al.* 2013; Hudak *et al.* 2016):

$$FC = FRE/rf/hc$$
 (1)

FC =
$$\frac{FRE}{(3.025 - 5.32 \times W_c)}$$
 (2)

where FC is consumption (kg m⁻²), hc is heat content (MJ kg⁻¹), rf is radiative fraction, and W_c is water content (%). Eqn 1 is an energy density-based approach that accounts for the heat content of the fuel and the proportion of energy released radiatively (Hudak *et al.* 2016). We used an rf of 17%, the mean radiative fraction of the 12 *Quercus* litter and woody debris experimental burns carried out by Kremens *et al.* (2012). The average heat content for all ponderosa fuel components was 20.86 MJ kg⁻¹ (Van Wagtendonk *et al.* 1998). Equation 2 comes from Smith *et al.* (2013). This moisture-based approach does not account for the effect of variable heat contents of fuel types and instead addresses the strong effect moisture has on radiative fraction and consumption (Smith *et al.* 2013).

Prescribed fire imagery acquisition and analysis

We collected data at three operational prescribed fires: two in Arizona; and one in Florida (Table 2). The prescribed fire sites were all composed of a fire tolerant Pinus species but displayed substantial variability in fuel loading, fire seasonality, and target fuel load reductions (Table 2). To collect data on prescribed fires in Arizona, we obtained permission from the USDA Regional Fire and Aviation Office to operate UAS and coordinated with local US Forest Service districts to attend approved prescribed fires. In Florida, the prescribed fire was on private land, so we coordinated with landowners to attend the fire. We adhered to the Federal Aviation Administration Part 107 rules and the safety regulations written in the US Forest Service research contract (when attending agency-administered prescribed fires). Sites were selected based on availability of prescribed fires during the 2022-2023 season. Prescribed fires were ignited in the Fall, Winter, and Spring and were within the target weather window described in the prescribed burn plans (see Supplementary material).

Prior to ignitions, we located plots that were representative of the fuel conditions of the prescribed fire sites. We placed plots near the perimeter of the fire, typically on opposite sides of the burn unit to capture multiple plots during one ignition operation. Plot size of the thermal imagery was variable, dependent on the UAS altitude, drift, and stability. Generally, plots were about 0.4 ha (Table 2). We placed four 40-cm diameter aluminium pans in each plot, one in the centre and three in the north, south, and west directions about 15-20 m from the centre pan (prioritising canopy openings to avoid occlusion). The pans acted as ground control points (GCPs), allowing us to continually fly the UAS over the same location, georectify images, and validate the georectification. Shiny aluminium contrasted the forest floor well and had a low emissivity, meaning the plates were clearly visible in the infrared and colour imagery. We used the pans to georectify the thermal image stacks and verify that the stabilisation and coregistration workflow produced acceptable results, as described below. At the Hanna Hammock Rx, we geolocated each pan using a real-time kinematics GPS with centimeter-level accuracy. At the Hundred Rx and Wild Bill Rx, we measured the distance between each GCP and inferred their coordinate position by orthorectifying pre-burn images of the plot via photogrammetry (Agisoft 2023). This method was centimetre-level accurate as well, but the geolocation was subject to the precision of the UAS GPS. We recorded the average daily fuel moisture of 10-h fuels from the nearest Remote Automated Weather Station, available from the Western Regional Climate Center (http://www.raws.dri.edu).

We used the best performing method from the calibration burn and the moisture-based approach (Eqn 2), to convert FRE to consumption for the prescribed fire plots. One challenge with monitoring with UAS is capturing post-frontal combustion (Moran *et al.* 2022), which may continue for hours or days after the burn. We balanced collecting as many plots as possible with capturing all possible postfrontal consumption by sampling about two plots per

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Site, state	Location (elevation, m)	Date	Forest type	Est. fuel load (kg m ⁻²)	Avg. fuel moisture (%)	No. of plots	No. of images (IR/RGB)	IR image location error (RMSE, m)	Avg. thermal sampling time (min)	Avg. plot (m ²)
Calibration Burn, A	z 35.173°N, 111.653°W (2100)	September 2023	Experimental	2.5–22	ш	10	1500	0.10	142	-
Hanna Hammock R)	<pre><, FL 30.660°N, 84.250°W (60)</pre>	February 2023	Longleaf pine	0.57 ^	15	2	800/400	1.93	38	4500
Hundred Rx, AZ	34.148°N, 110.813°W (2000)	April 2023	Ponderosa pine	3.4-4.5 ^B	4.2	2	1600/800	1.01	71	3900
Wild Bill Rx, AZ	35.322°N, 111.783°W (2400)	May & June 2023	Ponderosa pine		5.9	4	5500/1400	1.24	152	4100
- 										

all Timbers research program.

Tonto National Forest 2023 Burn Plan (see Supplementary material)

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operational shift, each plot being sampled until radiant energy release had substantially subsided. To estimate post-frontal combustion, we fit a linear regression with a logarithmic transformation of the plot FRP at each infrared image, in the image stack. Linear regressions were calculated for each burn:

$$\ln(\text{FRP}) = \beta_0 + \beta_1 \times t + \epsilon \tag{3}$$

where *t* is time. We fit the linear regression to the energy release from the peak energy release to the end of the image capture, which visually exhibited a logarithmic relationship. We then used this model to predict unmeasured energy release of the plots from when data collection stopped to when the theoretical energy release $\leq 1 \text{ W m}^{-2}$. Comparing the total energy (FRE) measured with the predicted unmeasured energy release gave us a corrective factor, which we applied to each consumption raster to account for any unmeasured energy. For example, if the regression predicted 20% of energy was not captured during collection, then each pixel would be multiplied by 1.2.

To estimate rate of spread, we used the masked FRP raster stack to generate an arrival time, or progression, raster of the fire when each pixel reached flaming power, 1070 W m⁻² (Hudak et al. 2016). The rate of spread was then derived as the rate of change or slope (radians) of the progression raster (Moore et al. 2020) using the equation:

$$ROS = \frac{1}{\tan(slope)} \times 60$$
 (4)

where ROS is measured in m min⁻¹. The slope raster was then converted to points and interpolated for all progression pixels using inverse distance weighing. Residence time was calculated as the total time (in seconds) that each pixel was greater than or equal to 300°C (Wotton et al. 2012).

Statistical analysis

To evaluate the effectiveness of UAS-IR imagery at capturing the 'signal' of prescribed fires, we assessed whether the spatial resolution could adequately characterise fire behaviour variability. In signal processing, the Nyquist criterion states the sampling interval (or resolution) should be twice that of the frequency in the sample (Shannon 1949; Hengl 2006). Therefore, we evaluated the resolution of the 'signal' to determine the resolution needed of the sensor. We constructed a semi-variogram of each plot's FRE raster to determine the spatial scale where autocorrelation was no longer significant. Then, we calculated the median semi-variogram range of all the plots and resampled each pyrometric raster to this value. We confirmed that autocorrelation was reduced with a Moran's I-test. These spatially-independent samples of all three pyrometrics were then compared to assess differences among prescribed burns with a nonparametric Kruskal-Wallis test. If the Kruskal-Wallis test indicated significant differences, we used the Dunn test, a *post hoc* test for non-parametric data, to determine specifically which burns were different from one another.

Results

We successfully collected 16 h of imagery of fire behaviour, stabilising and processing it into spatially explicit pyrometrics from three prescribed fires and one calibration burn. The average plot size of the thermal imagery was 0.41 ha (approximately square with 64-m sides) and the average duration of fire captured was 87 min (Table 2). The longest duration of thermal imagery was 3.5 h, captured at plot 3 of Wild Bill prescribed fire.

UAS-derived consumption

Observed weight-based consumption of the 10 1-m² plots ranged from 2.1 to 19 kg m⁻² with all plots consuming 95% or more of dry weight fuel (Table 1). We measured average litter and wood fuel moisture as 11%. UAS-based consumption estimates were in high agreement with observations across all plots (Fig. 1). Converting radiative energy using either Eqns 1 or 2 to consumption was highly correlated with observed consumption. However, using equation 1 from Hudak *et al.* (2016) consistently underpredicted consumption. The linear regression of observation as the response had a slope of 0.77 ($R^2 = 0.99$). Converting FRE using the fuel moisture approach from Smith *et al.* (2013), Eqn 2 was closer to a 1:1 relationship with a linear regression slope of 1.1 ($R^2 = 0.99$). Therefore, all estimates of consumption for the prescribed fires (Table 2) were generated with the Smith *et al.* (2013) equation (Eqn 2).

UAS-IR fire behaviour

Extracted pyrometrics from the UAS-derived IR imagery agreed with qualitative ocular observations of the burns: Hanna Hammock spread the fastest; and Hundred and Wild Bill prescribed fires consumed more fuel with longer residence times (Fig. 2). Predicted FRE using Eqn 3 to account for unmeasured FRP performed well, with strong model fits with the captured energy (Fig. 3). Plots where the UAS imagery collection captured enough post-frontal combustion that a decay curve was evident had the strongest model performance. At the Hanna Hammock plots, majority of the energy was released within 10-min, resulting in most energy being directly measured and only a minor fraction modelled with Eqn 3. The prescribed burns in Arizona continued to release significant energy for hours after the peak FRP and therefore the regression-based estimates of energy release were critical for estimating total energy released and consumption. Average total consumption for Hanna Hammock, Hundred, and Wild Bill were 0.3, 1.4, and 4.9 kg m⁻², respectively. The consumption data was heavily positively skewed (Fig. 4). Maximum within-plot consumption was 65 kg m⁻², sampled at plot 1 of the Wild Bill Rx. Median rate of spread was 2.5, 0.7, and 0.7 m min⁻¹ for Hanna Hammock, Hundred, and Wild Bill prescribed fires, respectively. Rate of spread reported by the UAS imagery ranged from 0.002 to 4.0 m min⁻¹, the maximum recorded at Plot 1 of Hanna Hammock and the minimum recorded in plot 4 of Wild Bill prescribed fire. Median residence time



Fig. 1. Calibration burn results from weight-based measurements of consumption and UAS-based consumption (left plot). Brown points (triangles) use Eqn 1 from Hudak *et al.* (2016) and green points use Eqn 2 from Smith *et al.* (2013). Linear regressions of observed as a function of predicted (observed ~ predicted consumption, solid lines) reveal a slight overprediction when applying Eqn 2 and an underprediction when applying Eqn 1. The density plot (right plot) highlights the variability of fire radiative energy (FRE) pixels of plot 1 (left image) and 10 (right image), with remaining plots represented as lines.



Fig. 2. Location and images of fire behaviour of the prescribed fires monitored (*a*), selected IR images and derived rate of spread raster of the Hanna Hammock plot 1 (*b*), and selected IR images and derived consumption raster of the Wild Bill plot 3 (*c*). Hanna Hammock Rx had the highest visually observed rate of spread and lowest consumption. Wild Bill Rx had a large amount of coarse woody debris present in plots and had the highest visually observed estimate of consumption and residence time.

was 40, 96, and 170 s for Hanna Hammock, Hundred, and Wild Bill prescribed fires, respectively.

Using a semi-variogram to identify autocorrelation for each plot's radiative energy (FRE) raster, we found the median range to be 4.6 m. Before resampling, FRE rasters of each plot had a median resolution of 0.13 m (Table 2) and Moran's *I*-value of 0.96, indicating a very strong positive autocorrelation. 35 pixels were resampled to 4.6 m resolution to minimise autocorrelation. Therefore, the Nyquist sampling theorem would suggest a sampling resolution of 2.3 m or less is needed to characterise the fire behaviour of prescribed fires. After spatial resampling (to 4.6 m), median Moran's *I*-value was reduced to 0.29: while spatial autocorrelation was still present, it was markedly reduced. A Kruskal–Wallis test of the resampled pyrometric data showed that each pyrometric had significantly



Fig. 3. Fire radiative power (W m⁻²) over time of each of the burn plots. Red dashed line is the logarithmic transformed linear regression and respective R^2 values denote model performance evaluated with measured energy data. Dark shaded area is the energy measured by the UAS-IR imagery, lightly shaded area is unmeasured energy predicted using the regression. Measured and predicted energy values were summed in the final consumption estimates. The green fine-dashed line in Wild Bill 4 plot represents a long pause (-1 h) in imagery collection during minimal, static fire activity. This particular plot was burned in early morning when conditions were relatively cool and wet, so fire intensity was particularly low. Ignition operations then made a second pass at 150 min, corresponding to the spike in fire radiative power.

different groups (Fig. 4). The *post hoc* Dunn tests showed that Wild Bill and Hundred groups were similar in terms of rate of spread or residence time distributions (Fig. 4), though all other Dunn tests were significant (P < 0.025).

Discussion

The preprocessing workflow developed to calibrate, stabilise, and georeference UAS-IR imagery was effective for deriving pyrometrics. We converted IR emittance to temperature using a bench-tested algorithm (Eqn S1) that performed well ($R^2 = 0.99$). Then, we selected the ECC-affine transformation model to stabilise image stacks with submeter drift. Finally, we georeferenced image stacks using GCPs with 1 m-level precision (average RMSE = 1.1 m).

Our calibration experiment demonstrated that estimating fuel consumption using UAS-IR imagery was accurate in a range of fuel loading conditions and could be applied to the prescribed fire IR imagery. The fuel moisture-based equation from Smith *et al.* (2013) (Eqn 2) was the best approach for our purposes. While reliable and often time consuming, traditional sampling methods for estimating consumption are not spatially explicit and are less accurate (Lutes *et al.* 2006; Sikkink and Keane 2008). This research suggested that UAS-IR imagery is an alternative option to measuring fuel consumption. While the calibration experiment was representative of the prescribed fire fuel and monitoring conditions, additional research is needed to validate *in-situ* consumption estimates in a range of fuel types, moisture contents, and arrangements.

Caution should be exercised when selecting a method to converting fire radiative energy to consumption. Previous research by Hudak *et al.* (2016) found the energy approach (Eqn 1) underestimated consumption, aligning with our results (Fig. 1). One possible source for the underestimated consumption was the fuel moisture present. In the context of thermal signal saturation, these results are also limited to the sensor tested because of the relatively low thermal sensor saturation temperature. While it is possible that the plots may have burned at temperatures greater than the saturation point, the high precision of Fig. 1 results suggest the sensor did not reach saturation or saturation was equal for each plot.

Pyrometrics derived from UAS imagery proved to be useful for prescribed fire evaluation and monitoring. Three prescribed fires were examined using thermal infrared imagery, yielding spatially explicit measurements of consumption, rate of spread, and residence time. From a qualitative standpoint, these measurements were consistent with ocular estimates of fire behaviour and effects, highlighting discernible variability among the burns (Fig. 4). The semivariograms illustrated that prescribed fire behaviour measured at each plot occurs at moderate scales (<4.6 m). The Nyquist Criterion states that to accurately sample a continuous signal and reconstruct it without aliasing, you must



Fig. 4. Violin distributions and boxplots of UAS-derived pyrometrics from each prescribed fire: Hanna Hammock Rx, Hundred Rx; and Wild Bill Rx. A significant Kruskal–Wallis rank sum test that two or more of the distributions are different is marked as an asterisk on the *x*-axis label. *Post hoc* Dunn tests to determine pairs of significantly different distributions are marked as asterisks on the *y*-axis label.

sample at least twice the frequency (or resolution) of the highest frequency component in the signal, suggesting sensor resolutions of less than 2.3 m are ideal. As prescribed fire is often affected by fine-scale processes, sampling at high temporal (>0.1 Hz) and spatial (<1 m^2) resolutions is imperative to capture the heterogeneity of pyrometrics (Moran et al. 2019). The sampling resolution will need to be considered for each fire and fuel type. For example, sampling at lower resolutions for moderate intensity, slow spreading fires in forested ecosystems will likely still capture the heterogeneity of fire behaviour. In grass-dominant fuel types though, high temporal sampling is critical to capture the brief peak in radiative power release when the grass fuel is combusting. We sampled fire behaviour at sub-meter resolutions, ensuring detailed spatial variability was captured. The Kruskal-Wallis and post hoc tests of the aggregated pyrometrics illustrated the variability of fire captured and also corroborated that our approach can effectively detect this variability and differentiate between prescribed burn pyrometrics (consumption, rate of spread, and residence time). While the intensities of the prescribed fires sampled were variable, fire effects were characteristic of low severity fire in their respective fire regimes (Table 2)

(Varner *et al.* 2005; Fulé *et al.* 2012). These sites captured a variety of prescribed fire dynamics in fire tolerant *Pinus* forests, representative of the many scenarios encountered in the US prescribed fire program. Future research could build off this work, testing this process in higher fuel loads and in other forest types.

We found that two out of the three evaluated prescribed fires likely achieved their objectives as far as can be determined from the 2–4 study plots in each fire. However, some of the burns lacked specific objectives related to fuel consumption. Hanna Hammock showcased the fastest rate of spread (peak and average spread) and lowest consumption (Fig. 4). Given a pre-fire fuel loading of 0.57 kg m⁻² (Table 2) and the consumption objective of 95% fuel reduction (see Supplementary material for details on burn objectives), desired consumption was 0.54 kg m⁻². We estimated consumption averaged 0.3 kg m⁻², 56% the desired objective. At this particular burn, adjacent research sampled preand post-burn fuel loading data of the site using 25 0.25 m^2 clip-plots (S. W. Bigelow, pers. comm.). Field fuel sampling inferred consumption to be 0.38 kg m⁻², or 66% of pre-burn fuel mass. This adjacent study corroborates our consumption estimate and presents solid evidence that the desired outcome of the burn, while stringent, was not achieved. At the Hundred Rx, 50-85% reduction in fuel loading was desired, approximately equal to $1-2 \text{ kg m}^{-2}$. UAS-IR consumption at the two plots sampled was estimated to be 1.1 and 1.6 kg m^{-2} , so consumption objectives were likely achieved. The Wild Bill Rx burn had significantly higher consumption than the other burns, estimated at 4.9 kg m⁻². Unfortunately, the burn plan only specified post-fire fuel loading (1.1–1.6 kg m⁻²) and not pre-fire fuel conditions or consumption, so direct comparisons were challenging. Given our consumption estimate and the desired post-fire fuel loading specified in the objectives, estimated consumption would equate to 75-81%. In similar forest types, desired consumption was specified to be 50-85% (Hundred Rx) and 40-80% (Waring et al. 2016) reduction in fuel loading. So, it is plausible that the Wild Bill Rx burn achieved consumption objectives, although there remains a degree of uncertainty.

A limitation of our study and the use of aerial infrared sensors was the occlusion of the thermal signal from tree canopy. Canopy foliage intercepted the thermal radiation of the fire, so we corrected for occluded radiative energy by masking pixels that did not exceed 1070 W m⁻² (see Supplementary material for more details). While the effect of canopy cover on radiative energy can be accounted for (Hudak *et al.* 2016; Mathews *et al.* 2016), caution should be exercised when estimating FRE in densely forested areas, especially when surface fuels are heterogeneous. Without the addition of other sources of sub-canopy fuel characteristics (lidar or ground measurements), our approach to monitoring prescribed fire requires unobstructed view of the surface fuels. We suggest our approach only be applied in areas with less than 75% canopy cover (which we adhered to

in our study) unless sub-canopy fuels are accounted for. Additionally, caution should be exercised when interpreting our results of rate of spread and residence times since these measurements were only compared to ocular estimates of fire behaviour as a means of validation at the eight prescribed fire plots. Future research quantitatively validating UAS-IR measurements of rate of spread and residence time and accounting for sub-canopy fire behaviour is recommended.

Researching prescribed fire during active incidents presented significant challenges. Often, burns were delayed, relocated, and difficult to access. Attending prescribed fires with UAS required extensive authorisation from the responsible agency, and Red Card qualified and FAA Part 107 certified researchers to operate a UAS over an active incident. The prescribed fires attended had a narrow window of favourable weather conditions and 1-3 day's notice of location and ignition time was typical. Collecting ground measurements was not possible with the limited time and resources available to us, though these scenarios represent the situations in which UAS may be implemented to monitor fire effects. Increasing our knowledge of prescribed fire and application of innovative technologies will require more research on active incidents and active collaboration between practitioners and researchers. Research-led development of software to automatically process UAS-IR imagery could provide faster results of prescribed burn effectiveness. Deriving and evaluating initial or rapidly-estimated pyrometrics directly from raw thermal images without extensive post-processing is a necessary research thread for achieving real-time pyrometrics and instantaneous feedback to managers.

Operationally, our findings support the efficacy of UASderived pyrometrics for monitoring and evaluating prescribed fires, specifically consumption, rate of spread, and residence time. We noted that the burn plans of the fires we attended contained broad objectives with wide ranges of desired outcomes. Refined fire monitoring coupled with refined objectives will be pivotal in informing fire management of best practices, justifying the use of prescribed fire, and providing quantitative feedback in an environment saturated with uncertainty. The application of prescribed fire is often subject to constraints due to concerns of disciplinary experts within agencies about the effect of fire on natural and cultural resources. Interdisciplinary cooperation would help prescribed fire to achieve objectives beyond fuel reduction. For example, detailed UAS-derived pyrometrics could be translated into estimates of belowground heat penetration (heat per unit area and residence time), affecting seed banks and root tissues, as well as aboveground energy release affecting canopy scorch and bole char (O'Brien et al. 2018). Wildlife habitat (Mason and Lashley 2021) and hydrological impacts (Flerchinger et al. 2016; Williams et al. 2020) can also be linked to fine-scale fire effects. The effect of prescribed burns on cultural resources such as fire-sensitive archaeological sites could be monitored in detail, allowing managers to assess whether prefire protection efforts such as clearing adjacent fuels were successful (Ryan 2010).

Supplementary material

Supplementary material is available online.

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Data availability. Data used to generate results of this study are available by request from the authors and through an online open-access portal (Hopkins B, O'Neill L, Marinaccio M, Rowell E, Parsons R, Flanary S, Nazim I, Afghah F, in prep.). Additionally, the code is available publicly on github (https://github.com/leo-oneill/Pyrometrics).

Conflicts of interest. Co-author Peter Fulé is an Associate Editor and did not take part in any editorial decisions about this manuscript to mitigate any conflict of interest. This has not affected our research or the peer-review process and the authors have no other conflicts of interest.

Declaration of funding. This research was funded by National Science Foundation (CPS-2039026) and Salt River Project (Award #8200007407).

Acknowledgements. This project would not have been possible without the help of multiple organisations and individuals including Preston Mercer and True Brown from Coconino National Forest; Jeremiah Boyd from Interagency Aviation Management Office; Karen Cummins, Morgan Varner, Seth Bigelow, and Vanessa Niemczyk from Tall Timbers Research Station; Andrew Nordquist from Tonto National Forest; and Floyd Hardin from Salt River Project.

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